Of Bats and Men

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animal "sonar" system

Observation [Spallanzani, 1794]

- navigation without vision
- assumption of an active system: echolocation



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Confirmation [Griffin & Pierce, 1938]

- acoustic navigation
- ultrasonic waves, of short duration (a few milliseconds) and large bandwidth (from 40 to 100kHz)

example of a pursuit recorded in the field (slowed down 32x)

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Hearing evidence

- "Chirping" transients
- Limitation of Fourier analysis

Beyond Fourier

- Time evolution of spectral features
- Wedding physical intuition and mathematics
- Development of *time-frequency* techniques

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Hearing evidence

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a typical sequence (Myotis mystacinus)...



... and its time-frequency reading



cruise, pursuit, catch



details



refined time-frequency analysis (reassignment)



optimality of a natural system?

Necessity of adapting to multiple tasks

- *detection* (obstacles, preys,...)
- estimation (range, velocity, bearing,...)
- recognition (scenes, targets,...)
- interference rejection (reverberation, other bats,...)

• ...

Why the observed signals?

- waveforms?
- evolution within a sequence?
- o physiological constraints?
- ...

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the perspective of man-made systems

Two "historic" families of active systems

- 1 sonar (acoustic waves) : Navy, fisheries,...
- *radar* (electromagnetic waves) : air controle, road traffic, wheather forecast,...)



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from natural to man-made systems, and back

A two-way approach

- Learn from Nature, towards artificial systems mimicking natural solutions
- 2 Apply to Nature concepts, models and evaluation criteria used in technological systems

Pros and cons

- A "natural" perspective on optimality
- The *"bionic temptation"* (e.g., planes vs. birds!)

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sonar/radar as a paradigm

Principle

- 1 target detection via presence of an echo
- ange estimation by time-of-flight measurement
- speed estimation from Doppler
- ④ bearing estimation by binaural reception
- (5) target characterization from *modifications* (attenuation, filtering) of the emitted signal

How?

comparaison by *correlating* signal and echo: *matched filtering*

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correlation

correlation

bearing

Doppler effect

Signal?

- physical outcome of some "useful" information
- characterized in a 1st approximation by properties in
 - time (duration,...)
 - frequency (bandwidth,...)

"Optimal" signals?

- mathematical properties of correlation
- accurate estimation of
 - range → large bandwidth
 - speed \rightarrow narrow bandwidth
- possible trade-off with *frequency modulated* signals ("chirps")

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Observation and interpretation

Cruise — Importance of estimating both *range* (delay) and *speed* (Doppler)
⇒ *large bandwidth* whistle + part with an *almost constant frequency*



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Observation and interpretation

• **Pursuit** — Importance of estimating *range* whatever the Doppler rate

 \Rightarrow matched whistle + *progressive suppression* of the part with an almost constant frequency



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Observation and interpretation

 Catch — Importance of maximizing the *emission rate* thanks to short duration signals
⇒ increase of the effective bandwidth by *lowering the pitch* and increasing distortion (*harmonics*)



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a time-frequency view of detection

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Doppler tolerance

Doppler tolerance



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a "built-in" matched filter?



J.A. Simmons et al., J. Comp. Phys. A (1990)

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a "built-in" matched filter!



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a "built-in" time-frequency matched filter?



to conclude

A general principle

- a signal *questions* a system (natural or man-made)
- 2 the system <u>answers</u> with an echo
- 3 the useful information is derived from a *comparison* between signal and echo

Multiple variations

- the example of Nature
- the *bionic* approach (and its limits...)

One quote [J. Fourier, 1811]

"L'étude approfondie de la nature est la source la plus féconde des découvertes mathématiques."

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